



Interevent time distribution, burst, and hybrid percolation transition

Cite as: Chaos **29**, 091102 (2019); <https://doi.org/10.1063/1.5121775>

Submitted: 27 July 2019 . Accepted: 28 August 2019 . Published Online: 17 September 2019

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ABSTRACT

Understanding of a hybrid percolation transitions (HPTs) induced by cluster coalescence, exhibiting a jump in the giant cluster size and a critical behavior of finite clusters, is fundamental and intriguing. Here, we uncover the underlying mechanism using the so-called restricted-random network model, in which clusters are ranked by size and partitioned into small- and large-cluster sets. As clusters are merged and their rankings are updated, they may move back and forth across the set boundary. The intervals of these crossings exhibit a self-organized critical (SOC) behavior with two power-law exponents. During this process, a bump is formed and eliminated in the cluster size distribution, characterizing the criticality of the HPT. This SOC behavior is in contrast to the critical branching process, which governs the avalanche dynamics of the HPT in the pruning process. Finally, we find that a burst of such crossing events occurs and signals the upcoming abrupt transition.

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Percolation transition (PT) is known as one of the most robust continuous transitions. Recently, it was revealed that global suppression is an indispensable factor for a discontinuous PT. It brings up another perspective: “what are the necessary factors for a hybrid PT (HPT)?” HPT is a discontinuous PT accompanied by one or more critical phenomena. Here, we uncovered the underlying mechanism and established a theoretical framework: we discovered not only a global suppression effect but also a new self-organized criticality (SOC), which lead to a discontinuity and determine a criticality of the hybrid PT. Dynamic critical exponents of the SOC are linked to the conventional static critical exponents of PT. This theoretical framework opens a new avenue for understanding tug-of-war-type critical dynamics.

Complex systems composed of a large number of interacting components are constantly adapting to the changing environment and sometimes reach critical states.^{1,2} In these states, complex systems may be statistically characterized by power-law distributions.³ Examples include the number of aftershocks per time step after the main earthquake,⁴ nonstationary relaxation after a financial crash,⁵ the number of fires with a certain area per time step as a function of the area in forest fires,^{6,7} and the interevent time (IET)

distribution in human activities.⁸ Such critical phenomena occur in a self-organized manner, but a single framework describing their underlying mechanisms has not yet been established.^{3,9,10} In contrast, in critical states of complex systems, a small external perturbation imposed on a system can lead to widespread failure of the system through avalanche dynamics.¹¹ Examples include blackouts in electric power-grid systems^{12–14} and firing in neuronal networks^{15,16} in real-world systems, and k -core percolation^{17–19} and disease contagion models^{20–22} in artificial model systems. In such cascade dynamics, the avalanche sizes of different events form a power-law distribution. These behaviors have been explained by a universal mechanism (the critical branching process), which was also observed in self-organized criticality in the Bak, Tang, and Wiesenfeld (BTW) model.^{23,24}

Avalanche dynamics can be clearly observed in k -core percolation. The k core of a network is a subgraph, in which degree of each node is at least k . To obtain a k -core subgraph, once an Erdős–Rényi (ER) random network composed of N nodes having links between two nodes with probability p is generated in the supercritical regime, all nodes with degrees less than k are deleted consecutively until no more nodes with degrees less than k remain in the system. The number of nodes deleted during these consecutive pruning processes is considered as the avalanche size. The fraction of nodes remaining

in the largest k -core subgraph is defined as the order parameter m , which decreases continuously with decreasing p at criticality. When p is chosen as a transition point p_c , the deletion of a node from an ER network can lead to collapse of the giant k -core subgraph. Thus, a hybrid percolation transition (HPT) occurs, which exhibits features of first-order and second-order phase transitions. The avalanche size distribution shows power-law decay as $P_a(s) \sim s^{-\tau_a}$, where $\tau_a = 3/2$ at p_c , similar to that in the BTW model. Furthermore, there exists a critical avalanche of size $O(N)$, which may correspond to the dragon king often noted in complex systems.^{3,25}

In contrast to the HPTs induced by cascading dynamics, HPTs in cluster merging dynamics (CMD) have received little attention. In this paper, we aim to investigate the underlying mechanism of the HPT on a microscopic scale using the so-called restricted Erdős-Rényi (r -ER) network.^{26,27} Then, we set up a theory of the HPT. The model contains a factor that suppresses the growth of large clusters. Accordingly, the type of percolation transition is changed to a discontinuous transition,²⁸ similar to the case in which the $1/r^2$ -type long-range interaction changes the transition type to the first-order type in the one-dimensional Ising model.²⁹ However, this factor alone does not guarantee the occurrence of critical behavior. Here, we uncover underlying mechanism and find a self-organized criticality which determines the critical behavior of the HPT induced by the CMD.

The CMD of the r -ER model proceeds in a dichotomous and asymmetric way. Initially, there are N isolated nodes. Clusters are formed as links are connected one-by-one between pairs of unconnected nodes under the rule given below. Clusters are ranked by size and classified into two sets, A and B , which contain a portion gN ($0 < g \leq 1$) of nodes of the smallest clusters and the remaining large clusters, respectively. Two nodes are selected for connection as follows. One node is chosen randomly from set A , and the other is chosen from among all the nodes. They are connected by a link unless they are already connected. Then, the classification is updated as the cluster rankings are changed. Time is defined as $t = L/N$, where L is the number of occupied links, and it is the control parameter of the r -ER model. This quantity differs from p in k -core percolation in the point that the CMD at a certain time t_1 successively follows the dynamics of previous times, whereas the avalanche dynamics at a certain p_1 may be independent of those at any previous $p > p_1$.

The nodes in set A have twice the opportunity to be linked compared to the nodes in set B ; small clusters in set A grow rapidly, and the resulting large clusters may move to B , whereas the smallest clusters among the clusters in set B that have never grown or are growing slowly are evicted to A . Accordingly, cluster coalescence occurs in a dichotomous way, and the growth of large clusters is practically suppressed. The effective suppression becomes global as the portion of the smallest clusters is selected from among clusters of all sizes. This factor leads to a discontinuous percolation transition.

We first consider cluster evolution on a macroscopic scale. In the early time regime, the order parameter $m(t)$ (the fraction of nodes belonging to the giant cluster) is $o(N)$, and the cluster size distribution $n_s(t)$ exhibits power-law decay in the small-cluster region, but exponential decay in the large-cluster region. As time proceeds, medium-size clusters accumulate and form a bump in the cluster size distribution $n_s(t)$, as shown in Fig. 1(a) and the supplementary material. Technically, we trace m instead of t in simulations to reduce large

sample fluctuations arising around the transition point of the HPT. We estimate a characteristic time t_a , around which a giant cluster of size $m_a N \sim O(N)$ emerges and the bump size becomes maximum. m_a denotes $m(t_a)$. Soon after that, $m(t)$ increases rapidly, as shown in Fig. 2(a). t_a is estimated numerically as explained in the supplementary material. At t_g , the order parameter $m(t_g)$ (denoted as m_g) is equal to $1 - g$. This means that set B is occupied by the giant cluster alone. Beyond t_g , the giant cluster size exceeds the capacity of set B . In this case, the giant cluster is regarded as belonging to set A , along with all the other clusters.²⁷ The boundary between the two sets is eliminated. Note that this rule was not clearly specified in the original half-restricted model;²⁶ however, this rule is necessary to reach a critical state at t_c . Therefore, the r -ER model reduces to the original ER model but with the $n_s(t_g)$ of finite clusters and the giant cluster.²⁷ As time proceeds further to a transition point t_c , the bump disappears completely, and the size distribution of finite clusters n_s exhibits a power-law decay, $n_s(t_c) \sim s^{-\tau}$ [Fig. 2(a)], where $\tau(g)$ varies continuously with the parameter g .²⁷ The order parameter at t_c is denoted as m_c . The interval $[t_a, t_c]$ has been revealed to be $o(1)$.²⁶ Therefore, the order parameter is regarded as discontinuous at t_c in the limit $N \rightarrow \infty$. For $t > t_c$, the order parameter increases continuously with the critical behavior, $m(t) - m_c \sim (t - t_c)^\beta$. A hybrid transition occurs in the order parameter. We divide the time interval $[0, t_g]$ into two windows. In $[0, t_a]$, n_s exhibits power-law decay with an extra bump, whereas during $[t_a, t_g]$, the bump shrinks, and the giant cluster grows drastically. These behaviors clearly indicate that these two intervals need to be considered separately.

Next, we consider cluster evolution microscopically. We check the evolution of the largest cluster size among all the clusters in set A , denoted as $s_A(t)$. We find empirically that $s_A \sim (t_g - t)^{-1/\sigma'}$ for $t \in [0, t_a]$, which is analogous to the relationship used in the conventional percolation theory. We measure the exponent σ' directly using the relation $\dot{s}_A/s_A \sim s_A^{\sigma'}$ [Fig. 1(c)], where the dot over s_A represents the time derivative. The exponent $\sigma'(g)$ is almost one for $g = 0.2$ but decreases slowly with increasing g , as shown in the supplementary material. Note that the value of σ' differs from σ , which is conventionally defined for the characteristic cluster size in the supercritical regime, where $\sigma = 1$ independent of g .²⁷ Interestingly, $s_A(t)$ is located around the peak position of the bump in $n_s(t)$ for different t but is implemented using the corresponding m value, as shown in Fig. 1(a). This behavior appears for different system sizes, as shown in Fig. 1(b). The peak at s_A implies that clusters with sizes similar to $s_A(t)$ are abundant in the system although the bump shrinks as t increases beyond t_a .

More specifically, we consider how a cluster c_i of size s_i evolves during the bump formation period $[0, t_a]$. A schematic illustration is presented in Fig. 3.

- (i) Suppose a cluster c_0 is evicted from set B to A at time t_0 . If $t_0 = 1$, cluster c_0 has size $s_0 = 1$ in set A . Next, c_0 is merged with other clusters and grows, but it is still small enough that it does not move to B .
- (ii) Until time t_1 , cluster c_0 grows and has size $s_0(t_1)$. At time t_1 , cluster coalescence occurs as $c_0 + c_j \rightarrow c_k$, and the cluster size changes as $s_k = s_0(t_1) + s_j$, where cluster c_j is in either set A or set B . We consider the case that the cluster size s_k becomes larger than $s_A(t_1)$, and thus cluster c_k moves to B .

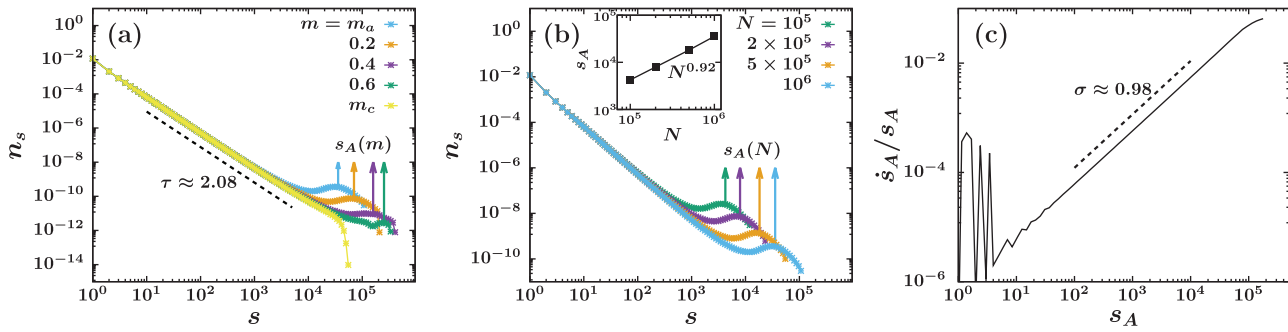


FIG. 1. (a) Cluster size distributions n_s , which is controlled by the corresponding cluster size cutoff m , at various times. s_A is located around the peak position of the bump for each time. $g = 0.2$ and $N = 10^6$. (b) System size dependence of n_s at m_a . The mean s_A grows with the system size N . Inset: $s_A(m_a)$ depends on N as $\sim N^{0.92}$. (c) To determine the exponent σ' of $s_A(t) \sim (t_g - t)^{-1/\sigma'}$, we plot \dot{s}_A/s_A vs s_A . $\sigma' \approx 0.98$ is obtained. Ensemble average is taken over 10^5 configurations.

(iii) Cluster c_k grows slowly to the size $s_{k'}$ in set B until time t_2 . If the size $s_{k'}$ becomes smaller than $s_A(t_2)$ for the first time, then cluster c_k is evicted to A . Then, the evolution returns to step (i).

This cycle is a prototypical pattern of cluster evolution up to the time t_a . During this cycle, small clusters (e.g., c_0) in set A have more opportunities to grow, whereas the growth of large clusters in set B (e.g., c_k) is suppressed. Accordingly, clusters of medium size become abundant and form a bump around $s_A(t)$, as shown in Fig. 1(a).

During the interval $t_a < t < t_g$, a nonnegligible amount of cluster coalescence occurs between a large cluster in set A and another large cluster in set A or the giant cluster in set B . In this case, step (iii) must also include the following event.

(iii') Cluster c_k of size $s_{k'}$ grows further by merging with clusters in set A , and $s_{k'}(t) \leq s_A(t)$ never occurs through t_g .

The cycle of steps (i)–(iii) is analyzed in terms of the duration time,⁸ how long a node remains in one set before switching to the other. Whenever a node i switches from one set to the other, its duration time is reset to zero. The update process of the duration time is described in detail in the [supplementary material](#). In Fig. 2(b), the horizontal axis denotes time, and the boundary between two domains (indicated by alternating use of color) represents an event in which a cluster of a given node i moves from one set to the other set. The interval between two consecutive boundaries is called the duration time (or IET) of node i and is denoted as z_i . Each node i can mark multiple set-crossing events and duration times on the timeline. The IET distribution $P_d(z)$ is constructed by accumulating these duration times over all nodes during a given time interval, for instance, $[0, t_g]$. We find that the IET distribution exhibits power-law decay as $P_d(z) \sim z^{-\alpha}$ [inset of Fig. 2(a)]. The exponent α depends on the

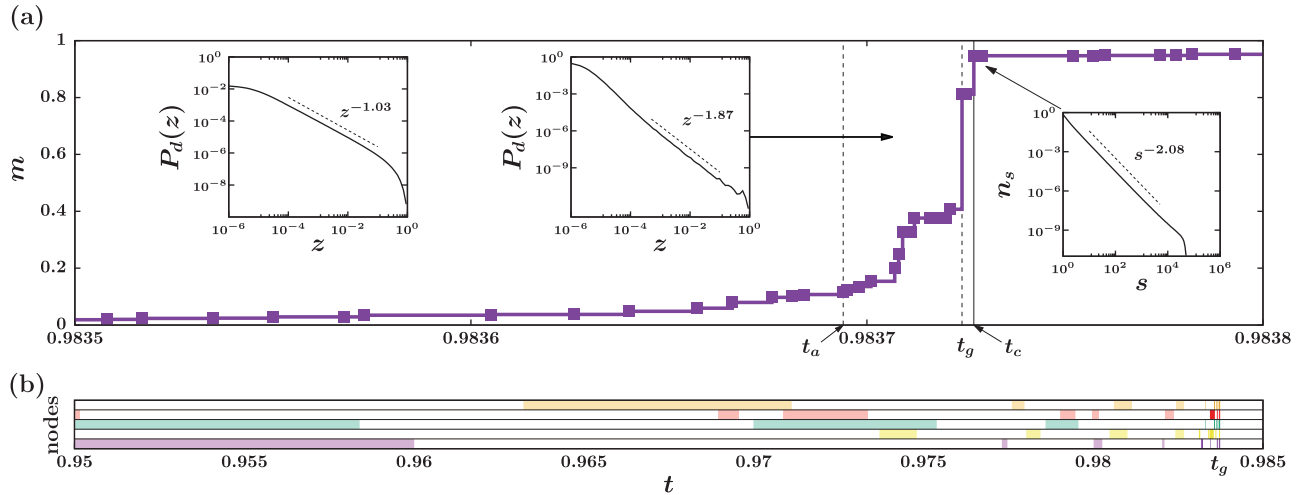


FIG. 2. Evolution of the giant cluster, IET, and burst: (a) typical staircase growth of the largest cluster size per node $m(t)$ for $g = 0.2$. The giant cluster of size $O(N)$ forms at time t_a and grows rapidly. Soon afterward, at t_g , it completely fills set B . Subsequently, the system follows ER dynamics and reaches a transition point t_c , at which $n_s(t_c) \sim s^{-\tau}$ (right inset) for finite clusters. The IET distributions $P_d(z)$ are accumulated in the intervals $[0, t_a]$ (left) and $[t_a, t_g]$ (middle), respectively. They exhibit power-law decays with the exponents $\alpha \approx 1.03$ and 1.87 , respectively. (b) A succession of interset A (colored) \leftrightarrow B (white) switching events demonstrate the bursty nature of this heavy-tailed process.

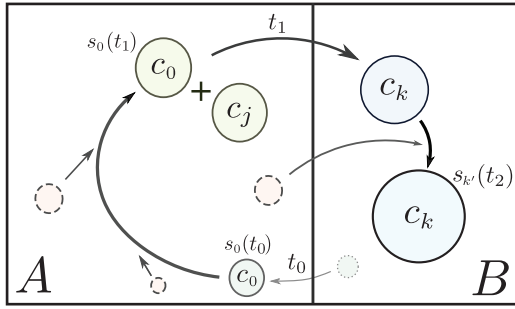


FIG. 3. Schematic diagram of a typical cluster lifecycle: A cluster is born with size s_0 and grows through coalescence. Each node of a cluster may have a different age (time since its birth). After sufficient growth in set A, a cluster is transferred to set B, where its growth is limited.

time window. For $[0, t_a]$, α is measured to be approximately one for $g = 0.2$, being insensitive to g as long as g is not close to one. This exponent value is also insensitive to the set-crossing type (either from A to B or from B to A). During the window $[t_a, t_g]$, the exponent α , alternatively denoted as α' , is found to be $\alpha' = 4 - \tau$ for the type $A \rightarrow B$ and is less than two. However, for the type $B \rightarrow A$, we obtain $\alpha' > 2$. We note that in the latter case, the duration times that were reset to zero before t_a remain, even though they are measured during the window $[t_a, t_g]$. Because the IET distribution for the window $[t_a, t_g]$ decays rapidly, the exponent α measured during the entire period $[0, t_g]$ is governed by the values measured during the window $[0, t_a]$, and thus, the exponent α is close to one.

We obtain the IET distribution analytically. Let us consider the case in which a cluster c_0 of size s_0 is evicted from B to A at time $t_0 > 0$. A node belonging to cluster c_0 has more opportunity to be selected. Thus, cluster c_0 grows rapidly in set A, and it returns to B for the first time at a time $t_1 = t_0 + z$, at which its size becomes larger than $s_A(t_1)$. Then, all s_0 nodes that belonged to the original cluster c_0 at time t_0 have duration time z , which is accumulated in the IET distribution. The probability $P_d^{A \rightarrow B}(z)$ that such events happen during the interval $[0, t_g]$ is calculated as

$$P_d^{A \rightarrow B}(z) = \int_0^{t_g} dt_0 s_0 q_1(s_0; t_0) \delta(s_0 - s_A(t_0)) \left[\prod_{t=t_0}^{t_0+z} q(s_{t_0+t}; t_0 + t) \right] \times [1 - q(s_{t_0+z}; t_0 + z)], \quad (1)$$

where $q_1(s_0; t_0)$ is the probability that a cluster of size s_0 in set B is evicted to set A at t_0 by an event in which a cluster larger than s_0 moves from A to B at t_0 . Further, $q(s_{t_0+t}; t_0 + t)$ is the probability that cluster c_0 remains in set A with size s_{t_0+t} at time $t_0 + t$. Next, we use the relation $s_A/\dot{s}_A = \sigma' s_A^{-\sigma'}$ and regard n_s as $\sim s^{-\tau}/(1 - s_A^{2-\tau})$ for $s \leq s_A$. Then, we obtain $P_d(z) \sim z^{-(4-\tau-\sigma')}$. A detailed derivation of the above equation is presented in the [supplementary material](#).

Next, we calculate the IET distribution $P_d(z)$ in $[t_a, t_g]$, which is composed of duration times that terminate in the interval $[t_a, t_g]$. During this short interval, the probability of selecting a cluster of size

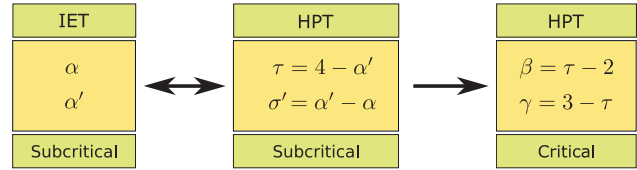


FIG. 4. The IET exponents α and α' determined in subcritical regime are related to the critical exponents τ and σ' of the cluster size distribution. And then, the exponent τ determines the critical exponents β and γ of the order parameter and susceptibility.

s may be regarded as $sn_s(t_g) \propto s^{1-\tau} e^{-s/s^*(t_g)}$, where $s^*(t_g)$ is constant, and thus $\sigma' = 0$. In this case, $P_d(z) = s \cdot sn_s |\partial s / \partial \langle z \rangle| \sim z^{-(4-\tau)}$. The exponent $\alpha' = 4 - \tau$ is in reasonable agreement with numerical results for the process $A \rightarrow B$, as shown in the [supplementary material](#). Note that the two relations, $\alpha = 4 - (\tau + \sigma') = 1$ for $[0, t_a]$ (and even for $[0, t_g]$) and $\alpha' = 4 - \tau$ for $[t_a, t_g]$, enable us to determine the static exponents τ and σ' for the cluster size distribution, once we have measured the dynamic exponents α and α' . Furthermore, the exponent τ determines the critical exponents β and γ associated with the order parameter and the susceptibility as $\beta = \tau - 2$ and $\gamma = 3 - \tau$, respectively.²⁷ Therefore, the IET exponents α and α' characterize the critical behavior of the HPT induced by cluster coalescence. We summarize these relationships in [Fig. 4](#).

Overall, we find that cluster interset-crossing events occur more frequently as time passes, as shown in [Fig. 2\(b\)](#). We examine the number of crossing events, denoted as $N_{\text{event}}(t)$, as a function of time by counting the number of nodes that switch from one set to the other at a given time t . We argue that $N_{\text{event}}(t) \sim 1/\langle z \rangle_s \sim s^*(t) \sim (t_g - t)^{-1}$ with some cutoff. Thus, a burst occurs in the interset-crossing as the time approaches t_g . Numerical data are presented in the [supplementary material](#). The burst may signal the upcoming HPT. We also find a Devil's staircase pattern during a short time period $[t_a, t_c]$.³⁰ More details are presented in the [supplementary material](#).

In summary, we have investigated the underlying mechanism of the HPT induced by cluster merging dynamics using the r -ER model, finding that the IETs between two consecutive set-crossing times have two distributions with power-law decays. This implies that there exists a self-organized critical (SOC) behavior previously unrecognized in the HPT. We established a theoretical framework for the HPT, analogous to the conventional percolation theory, and showed that the exponents of the IET distributions determine the critical behavior of the HPT. Finally, we note that the r -ER model can be extended to reverse dynamics, i.e., cluster disintegration processes. We find that there can exist several cluster disintegration rules with some suppression. Our preliminary results show that features of the cluster disintegration dynamics are nonuniversal, sensitive to the details of disintegration rules. Accordingly, we need further systematic analysis, and results will be published in somewhere else.

SUPPLEMENTARY MATERIAL

See the [supplementary material](#) for further details. In the [supplementary material](#), we present the method of determining m_a ,

maximal bump height at m_c , analytic solutions of the IET distribution, the age distribution in the birth-death process of ER networks, burst, the Devil's staircase pattern, and a table of the exponents.

ACKNOWLEDGMENTS

B.K. thanks H. J. Herrmann for useful discussions. This work was supported by the National Research Foundation of Korea (NRF) through Grant Nos. NRF-2014R1A3A2069005 (B.K.), 2017R1A6A3A11031971 (S.Y.), and 2017R1A6A3A11033971 (D.L.). We thank an anonymous referee for issuing the cluster disintegration process.

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Supplementary Material for Interevent Time Distribution, Burst, and Hybrid Percolation Transition

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(Dated: July 27, 2019)

In the Supplementary Material, we present S1) the method of determining m_a , S2) maximal bump height at m_a , S3) analytic solutions of the inter-event time (IET) distribution, S4) the age distribution in the birth-death process of ER networks, S5) the number of events, S6) the Devil's staircase pattern, and S7) a table of the exponent values characterizing the cluster size distribution, IET distribution, and the Devil's staircase.

S1. DETERMINATION OF m_a

First, we determine t_a as the intercept with the t axis of the tangential line of $m(t)$ at the inflection point of $m(t)$ in the region $0 < t < t_c$ onto the x axis. Then $m_a = m(t_a)$ (Fig. S1).

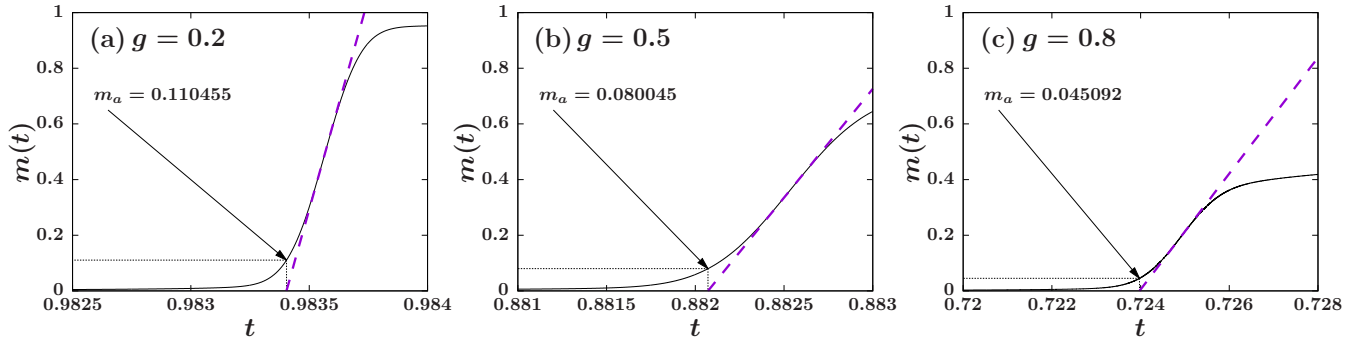


Fig. S1. Determination of m_a for different g values. First, we determine t_a as the intercept with the t axis of the tangential line of $m(t)$ at the inflection point of $m(t)$. Then $m_a = m(t_a)$.

S2. MAXIMAL BUMP HEIGHT AT t_a

A power law slope of n_s is slowly developed as the r -ER dynamics proceeds. Around the time t_a , the height of bump becomes maximum as shown in Fig. S2, and a giant cluster of size $m_a N \sim O(N)$ emerges as in the explosive percolation [1]. From then the giant cluster size rapidly increases during the interval $[t_a, t_c]$ of $o(N)$, which signifies a discontinuous transition in the thermodynamic limit. At the same time bump erodes away and a pure power-law cluster size distribution is formed at t_c .

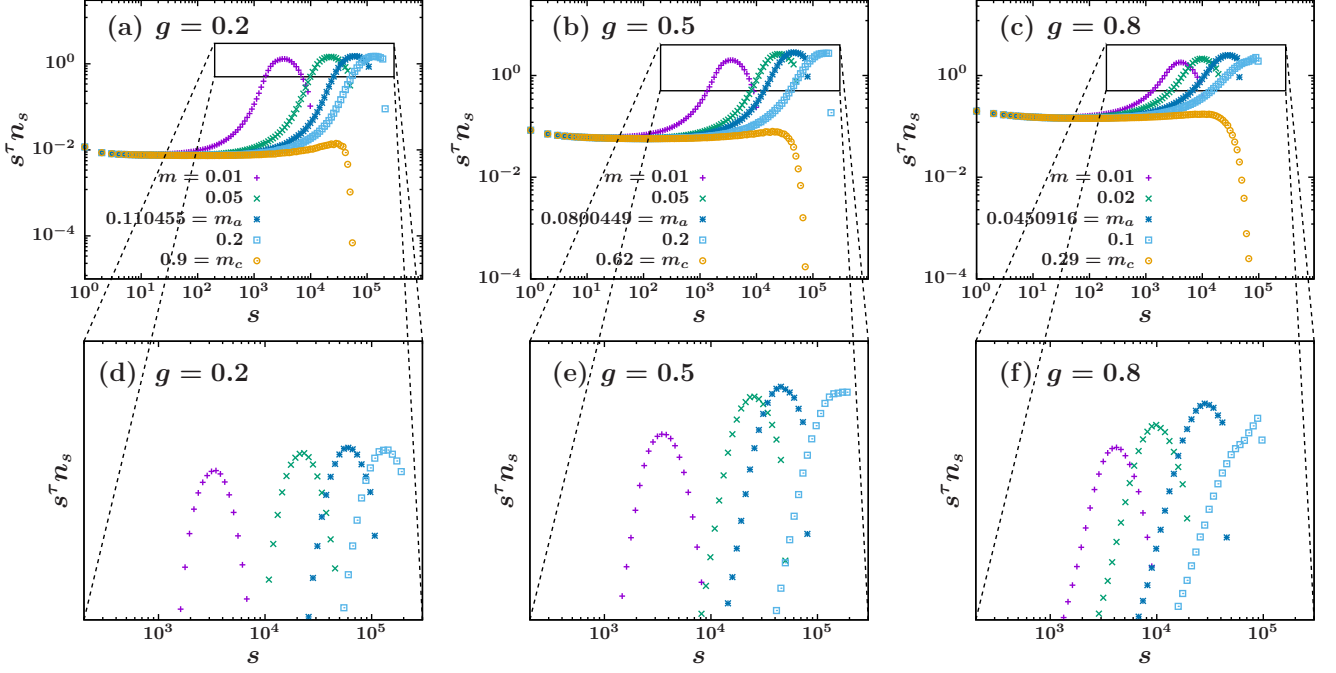


Fig. S2. Plot of $s^\tau n_s$ versus s at various values of m . (a–c) A power-law behavior of n_s is developed in small- s region before t_a and the region is elongated as time proceeds. Bump height seems to be maximum around m_a , and as time proceeds further, the right side of the bump is eroded as shown in zoom-in figures (d–f).

S3. THE INTER-EVENT TIME DISTRIBUTION

We assign a duration time z_ℓ to each node ℓ . Initially, at $t = 0$, $z_\ell = 0$ for each node ℓ . The duration time of each node ℓ is updated at each time step as follows: Suppose two nodes i and j are selected from the system under the given rule at a given time t . Here unit time is taken as $1/N$.

- i) If the two selected nodes belong to the same cluster in set A , they are connected unless there is already a link. The duration times of all nodes in the system $\ell \in A, B$ are increased by a unit time $z_\ell \rightarrow z_\ell + 1/N$. The constituent nodes and cluster sets of the system remain the same.
- ii) If the two nodes belong to two distinct clusters c_i and c_j of sizes s_i and s_j , respectively, in set A , then they are connected. Accordingly, the two clusters are merged into a new cluster c_k of size $s_k = s_i + s_j$.
 - ii-1) If $s_k \leq s_A$, then cluster c_k remains in set A . The duration times of each node ℓ in both sets are updated as $z_\ell \rightarrow z_\ell + 1/N$. The constituent nodes of both sets remain the same. Note that as a result of this coalescence process, nodes in the same cluster c_k have different duration times.
 - ii-2) If $s_k > s_A$, cluster c_k is moved to B , and an approximately same mass of clusters is transferred from B to A , in order to retain the mass restrictions of sets A and B . Consequently, one or two of the smallest clusters in set B are ejected to A . The duration times of all the emigrant nodes are accumulated in the IET distribution $P_d(z)$ and then reset to zero. The duration times of all the other nodes are updated as $z_\ell \rightarrow z_\ell + 1/N$. s_A may or may not be increased depending on the sizes of the ejected clusters.
- iii) If the two selected nodes belong to clusters $c_i \in A$ and $c_j \in B$ of sizes s_i and s_j , respectively, the duration times z_i of each node $i \in c_i$ are accumulated in the IET distribution $P_d(z)$, and then those duration times are reset to zero ($z_i = 0$). The duration times of each node j in cluster c_j are updated as $z_j \rightarrow z_j + 1/N$. The two clusters are merged, generating a cluster c_k of size $s_i + s_j$ in B . One of the smallest cluster in B , denoted as c_ℓ , is ejected to A , and the duration times of each node in c_ℓ are accumulated in $P_d(z)$. Then they are reset to zero.

The IET distribution can be constructed by collecting these duration times over all nodes during a given time interval, for instance, $[0, t_g]$. We find that the IET distribution exhibits power-law decay as $P_d(z) \sim z^{-\alpha}$. The exponent α is close to unity for $g = 0.2$ and 0.5 ; for such small values of g , the exponent appears to be insensitive to

changes in g . However, the exponent α is sensitive to the time interval in which the IET distribution is accumulated. When we accumulate the IET distribution during the interval $[0, t_a]$, $\alpha \approx 1$, but for the interval $[t_a, t_g]$, $\alpha' \approx 4 - \tau$. The reason is the different dynamics during each interval. Because the IET distribution decays rapidly in the interval $[t_a, t_g]$, the exponent α for the distribution accumulated in the interval $[0, t_g]$ is close to one.

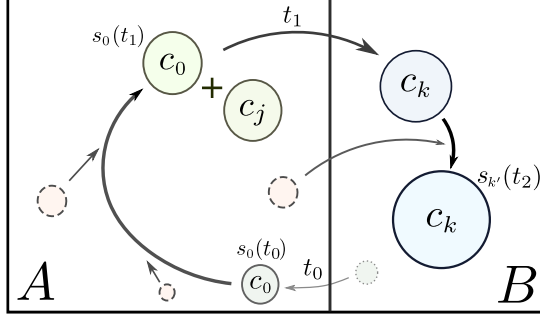


Fig. S3. Schematic diagram of a typical cluster lifecycle. A cluster is born with a size s_0 and grows through coalescence. Each constituent node of a cluster may have a different age (time since its birth). After sufficient growth in set A , a cluster is transferred to set B , where its growth is limited. We measure the duration time a node spends in one set before it moves to the other set. $s_A(t)$ is the maximum size of the clusters in set A at time t , which divides the system into the two sets A and B . It also increases with time.

We consider in detail the behavior of the IET distribution for the duration in set A , which is denoted as $P_d^{A \rightarrow B}(z)$. Let us consider the case in which a cluster c_0 of size s_0 moves from B to A at time $t_0 > 0$. Cluster c_0 grows in A as it is subsequently merged with other clusters, and then it returns to B at time $t_1 = t_0 + z$, because its size becomes larger than $s_A(t_1)$. $s_A(t)$ is the maximum size of the clusters in set A at time t , which divides the system into the two sets A and B . It increases with time. Then s_0 nodes that belonged to the original cluster c_0 at time t_0 have duration time z in set A . The evolution of cluster c_0 is depicted schematically in Fig. S3. Each constituent node of a cluster may have a different IET. After sufficient growth in set A , a cluster is transferred to set B , where its growth is limited. We measure the duration time a node spends in one set before it moves to the other set. The probability $P_d^{A \rightarrow B}(z)$ that such events happen is calculated as

$$P_d^{A \rightarrow B}(z) = \int_0^{t_g} dt_0 s_0 q_1(s_0; t_0) \delta(s_0 - s_A(t_0)) \left[\prod_{t=1/N}^{z-1/N} q(s_{t_0+t}; t_0 + t) \right] [1 - q(s_{t_0+z}; t_0 + z)] \quad (S1)$$

where $q_1(s_0; t_0)$ is the probability that a cluster of size s_0 in B makes way for some other immigrant cluster from A and is ejected to A at time t_0 . The probability q_1 is given as

$$q_1(s_0; t_0) = 1 - \sum_{i+j \leq s_0} \frac{in_i(t_0)jn_j(t_0)}{g}. \quad (S2)$$

Further, $q(s_{t_0+t}; t_0 + t)$ is the probability that cluster c_0 remains in set A with size s_{t_0+t} at time $t_0 + t$. For it to remain in set A , it is necessary that $u < t$, $s_{t_0+u} \leq s_A(t_0 + u)$. $q(s_t; t_0 + t)$ is calculated as follows:

- (i) Let the size of cluster c_0 at $t_0 + t - 1$ be denoted as s_{t_0+t-1} . A node in this cluster is selected at $t_0 + t - 1$ from among all nodes in set A with probability s_{t_0+t-1}/gN . Next, a node is selected from a cluster of size j in the entire system, which occurs with probability $jn_j(t_0 + t - 1)$. At time $t_0 + t$, the two nodes are linked, generating a cluster of size $s_{t_0+t} = s_{t_0+t-1} + j$. This size needs to be less than or equal to $s_A(t_0 + t)$. This occurs with probability

$$\frac{s_{t_0+t-1}}{gN} \sum_{j=1}^{s_A(t_0+t)-s_{t_0+t-1}} jn_j(t_0 + t - 1). \quad (S3)$$

We find the same probability in an alternative way of choosing these clusters. Thus,

$$\tilde{q}_1(s_{t_0+t}, t_0 + t) = 2 \frac{s_{t_0+t-1}}{gN} \sum_{j=1}^{s_A(t_0+t)-s_{t_0+t-1}} jn_j(t_0 + t - 1). \quad (S4)$$

(ii) We consider the case that cluster c_0 of size s_{t_0+t-1} is not selected at time $t_0 + t$, which occurs with probability

$$\tilde{q}_2(s_{t_0+t}, t_0 + t) = [1 - (s_{t_0+t-1}/gN)][1 - (s_{t_0+t-1}/N)] \quad (\text{S5})$$

$$\approx 1 - (1 + g) \frac{s_{t_0+t-1}}{gN}, \quad (\text{S6})$$

where we ignore the correction terms of higher order, $O(N^{-2})$. Together,

$$q(s_{t_0+t}, t_0 + t) = \tilde{q}_1(s_{t_0+t}, t_0 + t) + \tilde{q}_2(s_{t_0+t}, t_0 + t). \quad (\text{S7})$$

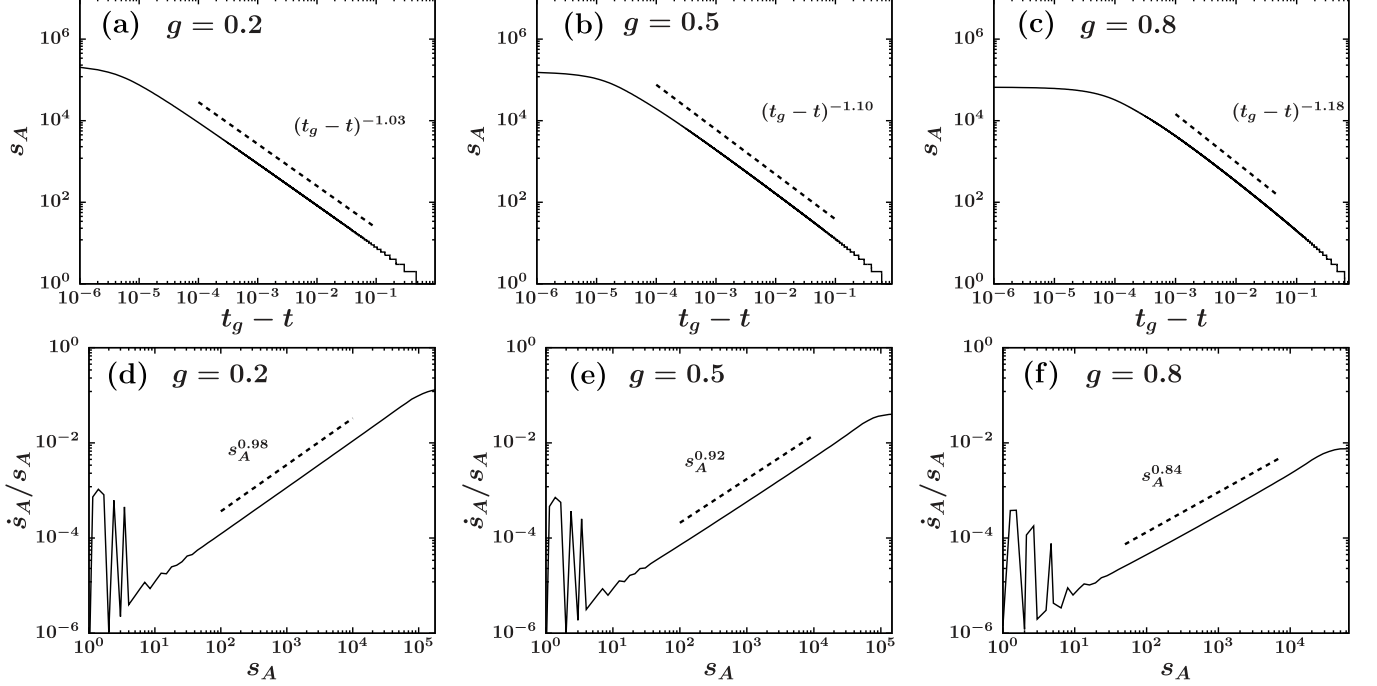


Fig. S4. (a–c) Dynamic scaling of $s_A \sim (t_g - t)^{-1/\sigma'}$ for different g values. (d–f) \dot{s}_A / s_A versus s_A . The curves were averaged over 10^5 configurations.

The product $\prod_{t=1}^{z-1} q(s_{t_0+t}; t_0 + t)$ depends on the full history of the size evolution of a cluster that was born with size s_0 at time t_0 and grew during the duration time z .

To calculate Eq. (S1), we consider the largest cluster size $s_A(t)$ at time t averaged over different realizations. We find numerically, as shown in Fig. S4 (a–c), that

$$s_A(t) \sim (t_g - t)^{-1/\sigma'} h\left(\frac{t_g - t_a}{t_g - t}\right), \quad (\text{S8})$$

where $h(x)$ is a scaling function, defined as $h(x) \sim x^{-1/\sigma'}$ for $x < 1$ and may be regarded as constant for $x > 1$ and σ' depends on the control parameter g . This gives an alternative form in the region $t \in [0, t_a]$,

$$\frac{\dot{s}_A}{s_A} = \sigma'(t_g - t) \sim \sigma' s_A^{-\sigma'}. \quad (\text{S9})$$

To calculate q_1 and q , we need the explicit form of the cluster size distribution $n_s(t)$. Even though the cluster size distribution includes a bump in the medium-size region centered at $s_A(t)$, we ignore the contribution of the bump to the probabilities q and q_1 without losing the essence. Moreover, we take the power-law region up to $s_A(t)$. That is, $n_s(t) \sim s^{-\tau}$ for $s \leq s_A(t)$, where τ depends on g (Fig. S5 (a–c)). Then, from the normalization $\sum_{s=1}^{s_A} s n(s, t) = g$, it follows that

$$n_s(t) = \frac{g(\tau - 2)}{1 - s_A^{2-\tau}(t)} s^{-\tau} \equiv C_A s^{-\tau}, \quad (\text{S10})$$

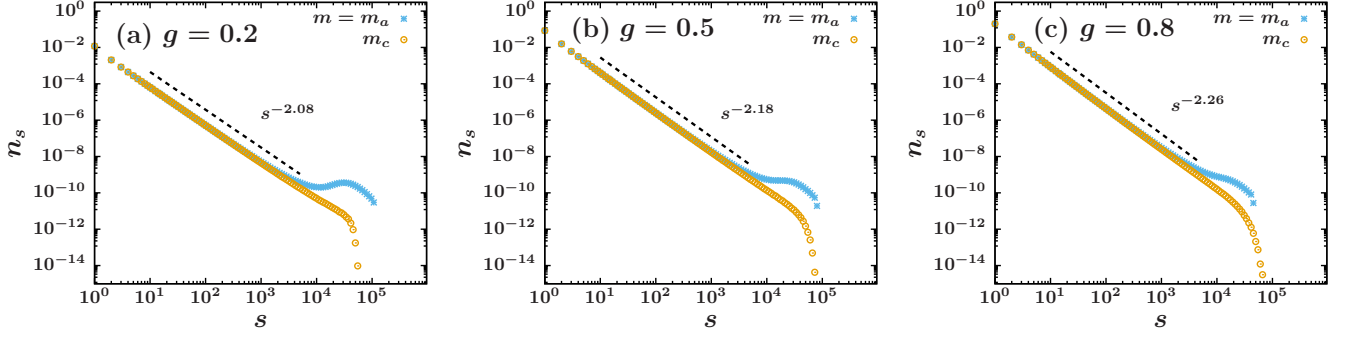


Fig. S5. (a–c) Cluster size distribution $n_s(t)$ versus s for $g = 0.2, 0.5$, and 0.8 at $t = t_a$ and t_c , which correspond to $m = m_a$ and m_c , respectively.

where C_A is the normalization factor of the cluster size distribution in set A . Now we introduce the probability of having selected two nodes in set A :

$$w_0(s, t) \equiv \frac{1}{g} \sum_{i+j \leq s} in_i(t)jn_j(t) \simeq \frac{1}{g} \int_1^s di in_i(t)M_1(s-i, t), \quad (\text{S11})$$

where $M_1(s, t) = \sum_{j=1}^s jn_j(t)$ is the accumulated mass function in set A , which satisfies the normalization $M_1(s_A, t) = g$. In particular, when $s \rightarrow s_0 \approx s_A$ in $q_1(s_0, t_0)$,

$$w_0(s, t) \approx \frac{1}{g} \int_1^s di in_i(t)M_1(s_A - i, t), \quad (\text{S12})$$

$$w_1(s, t) \equiv \frac{2s}{gN} \sum_{j=1}^{s_A(t)-s} jn_j(t) \xrightarrow{s \rightarrow s_0} \frac{2}{Nn_s} \frac{dw_0(s)}{ds}. \quad (\text{S13})$$

Then,

$$q_1(s_0, t_0) = 1 - w_0(s_0, t_0), \quad (\text{S14})$$

$$q(s, t) = \tilde{q}_1(s, t) + \tilde{q}_2(s, t) = \frac{2s^\tau}{NC_A} \frac{dw_0(s)}{ds} + \left[1 - \frac{(1+g)s}{gN} \right]. \quad (\text{S15})$$

Next, $w_0(s)$ is calculated as

$$w_0(s) \approx \frac{g}{(1 - s_A^{2-\tau})^2} \left[1 - 2s^{2-\tau} + C_\tau s^{4-2\tau} - \frac{(\tau-2)(4-\tau)}{3-\tau} s^{1-\tau} + (\tau-2)(3-\tau)s^{-\tau} + \dots \right], \quad (\text{S16})$$

where

$$C_\tau \equiv \frac{\Gamma(3-\tau)\Gamma(3-\tau)}{\Gamma(5-2\tau)} = \frac{\sqrt{\pi}4^{\tau-2}\Gamma(3-\tau)}{\Gamma(\frac{5}{2}-\tau)}. \quad (\text{S17})$$

Then q_1 and q are approximated to be stationary in time and only kept up to the leading orders :

$$q_1(s) \approx 1 - g, \quad (\text{S18})$$

$$q(s) \approx 1 - \frac{1+5g}{gN}s + \frac{4C_\tau}{N}s^{3-\tau} - \frac{2}{N} \frac{(\tau-1)(4-\tau)}{3-\tau} + O(s^{-1}, s_A^{2-\tau}). \quad (\text{S19})$$

The IET distribution in Eq. (S1) is obtained as

$$P_d^{A \rightarrow B}(z) \simeq \int_1^{s_A(t_g)} ds_A(t_0) \frac{1}{ds_A/dt_0} s_0 q_1(s_0; t_0) \delta(s_0 - s_A(t_0)) \left[\prod_{t=1/N}^{z-1/N} q(s_{t+t_0}; t_0 + t) \right] [1 - q(s_{t_0+z}; t_0 + z)] \quad (\text{S20})$$

$$\simeq \sigma' \int_1^{s_A(t_g)} ds_0 s_0^{-\sigma'} q_1(s_0; t_0) \left[\prod_{t=1/N}^{z-1/N} q(s_{t_0+t}; t_0 + t) \right] [1 - q(s_{t_0+z}; t_0 + z)], \quad \text{for } z > 1/N \quad (\text{S21})$$

$$\sim \frac{(1-g)\kappa\Gamma(2-\sigma')N^{\sigma'-2}}{\alpha(\log \frac{1}{1-A})^{2-\sigma'}} \left[z^{\sigma'-2} + \frac{B}{1-A} \frac{\Gamma(5-\sigma'-\tau)N^{\tau-2}}{\Gamma(2-\sigma')} \frac{1}{(\log \frac{1}{1-A})^{3-\tau}} z^{\sigma'+\tau-4} \right] e^{-z/z_c} \quad (\text{S22})$$

$$\sim z^{-(4-\tau-\sigma')} e^{-z/z_c}, \quad (\text{S23})$$

where $\kappa \equiv \dot{s}_t/s_t$, $A \equiv (1+5g)/(gN)$, $B \equiv 4C_\tau/N$, and $z_c = (3-\tau)/[2(\tau-1)(4-\tau)]$. We remark that in the second line to third line, we used the approximations (S18) and (S19). Then it is noticed that the (S21) corresponds to an integral representation of incomplete beta function. This integral can asymptotically evaluated as in (S22) for sufficiently large upperbound of the integral $s_A(t_g) \gg 1$. Moreover, in the limit of large interval z we have the asymptotic expression (S23). Therefore, we finally obtain the relation

$$P_d^{A \rightarrow B}(z) \sim z^{-\alpha} \sim z^{-(4-\tau-\sigma')}. \quad (\text{S24})$$

In the main text, we argue that $\tau + \sigma' = 3$. Thus, $\alpha = 1$. In Fig. S6, we show that this analytic result is consistent with numerical data.

S3.1. Waiting time distribution

Here we calculate the IET distribution $P_d(z)$ by an alternative method. We consider the mean waiting time steps $Z \equiv zN$ of a cluster of size s in set A until it is chosen.

$$\langle Z \rangle = \int_0^\infty dZ Z \left(1 - \frac{s}{N}\right)^Z \left(1 - \frac{s}{gN}\right)^Z \cdot \left[\frac{s}{gN} \left(1 - \frac{s}{N}\right) + \frac{s}{N} \left(1 - \frac{s}{gN}\right) \right] \quad (\text{S25})$$

$$\simeq \frac{(1+g)s}{gN} \int_0^\infty dZ Z e^{-\frac{(1+g)s}{gN}Z} \quad (\text{S26})$$

$$= \frac{gN}{(1+g)s}. \quad (\text{S27})$$

Using this property, we calculate the IET distribution $P_d^{A \rightarrow B}(z)$ as

$$P_d(z) \sim s \cdot sn_s \left| \frac{\partial s}{\partial z} \right|. \quad (\text{S28})$$

During the entire period $[0, t_g]$, the mean cluster density $\langle n_s(t) \rangle = (1/t_g) \int_0^{t_g} dt s^{-\tau} f(s/s^*(t))$, where $s^*(t) \sim (t_c - t)^{-1/\sigma'}$. $s^*(t)$ may be replaced by $s_A(t) \sim (t_g - t)^{-1/\sigma'}$. Dimensional analysis obtains

$$\langle n_s(t) \rangle = \frac{1}{t_g} \int_0^{t_g} dt s^{-\tau} f(s(t_g - t)^{1/\sigma'}) \quad (\text{S29})$$

$$= \frac{s^{-\tau}}{t_g} \int_0^{t_g} dt f(st^{1/\sigma'}) \quad (\text{S30})$$

$$= \frac{s^{-\tau-\sigma'}}{t_g} \int_0^{st_g^{1/\sigma'}} dy y^{\sigma'-1} f(y) \quad (\text{S31})$$

$$\sim \frac{s^{-\tau-\sigma'}}{t_g} \int_0^\infty dy y^{\sigma'-1} f(y). \quad (\text{S32})$$

where we asymptotically calculate the integral in the last line, using the assumption that f decays exponentially at large y . Therefore,

$$P_d(z) \sim z^{-(4-\tau-\sigma')}. \quad (\text{S33})$$

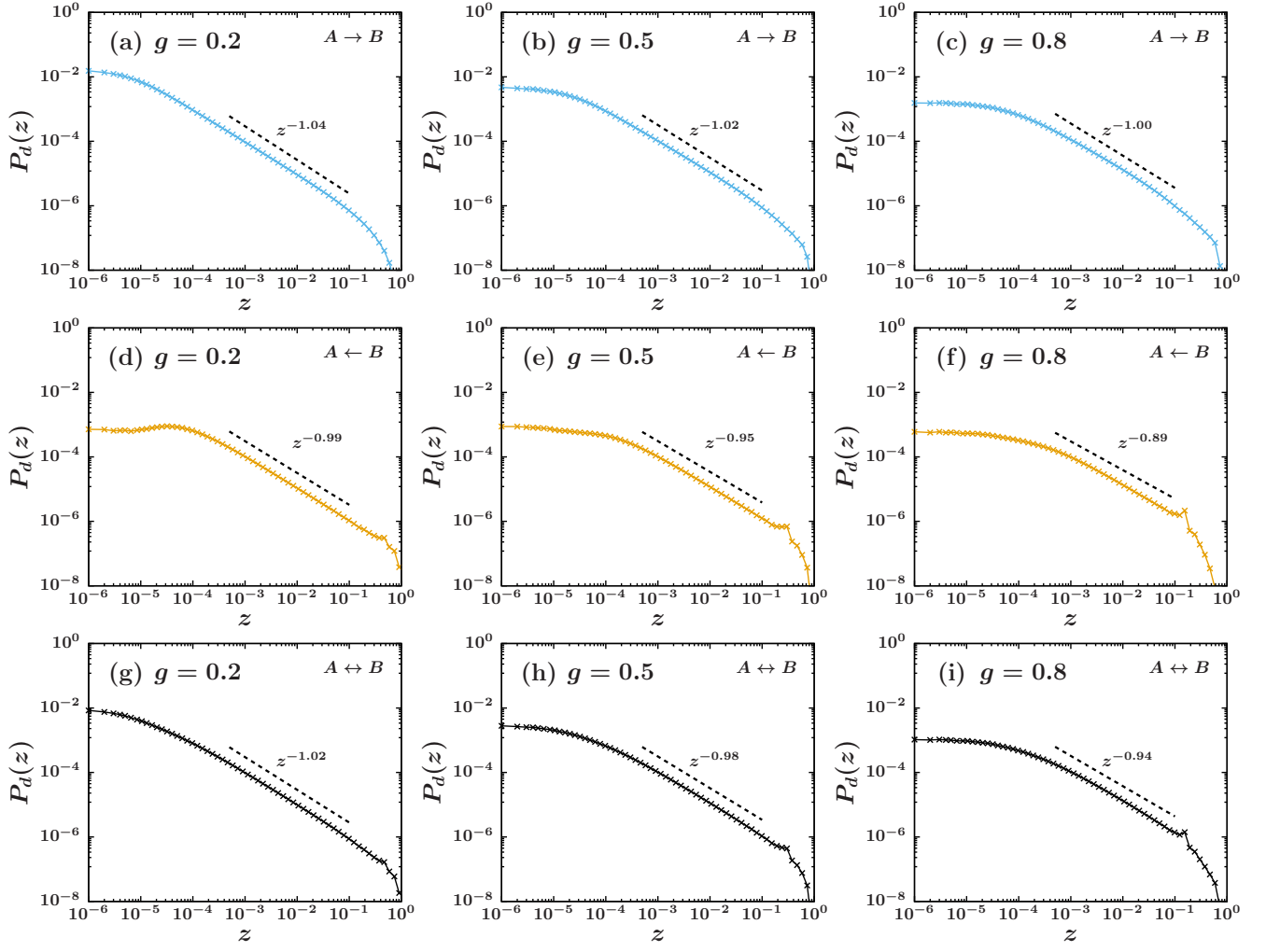


Fig. S6. IET distributions accumulated in $t \in [0, t_a]$. The exponent α is modified only slightly, depending on the direction of switching: (a–c) $P_d^{A \rightarrow B}(z)$, (d–f) $P_d^{A \leftarrow B}(z)$, and (g–i) $P_d^{A \leftrightarrow B}(z)$.

During the short time window $[t_a, t_g]$, a cluster of size s is selected with a probability proportional to $sn_s(t_g) \propto s^{1-\tau} e^{-s/s^*(t_g)}$ at each time step. Nodewise counting in the IET distribution measurement additionally introduces a multiplication factor of s . Therefore,

$$P_d(z) = s \cdot sn_s \left| \frac{\partial s}{\partial z} \right| \sim s^{4-\tau} \sim z^{-(4-\tau)} \equiv z^{-\alpha'}. \quad (\text{S34})$$

This result is in good agreement with the numerical results shown in Fig. S7 (a–c).

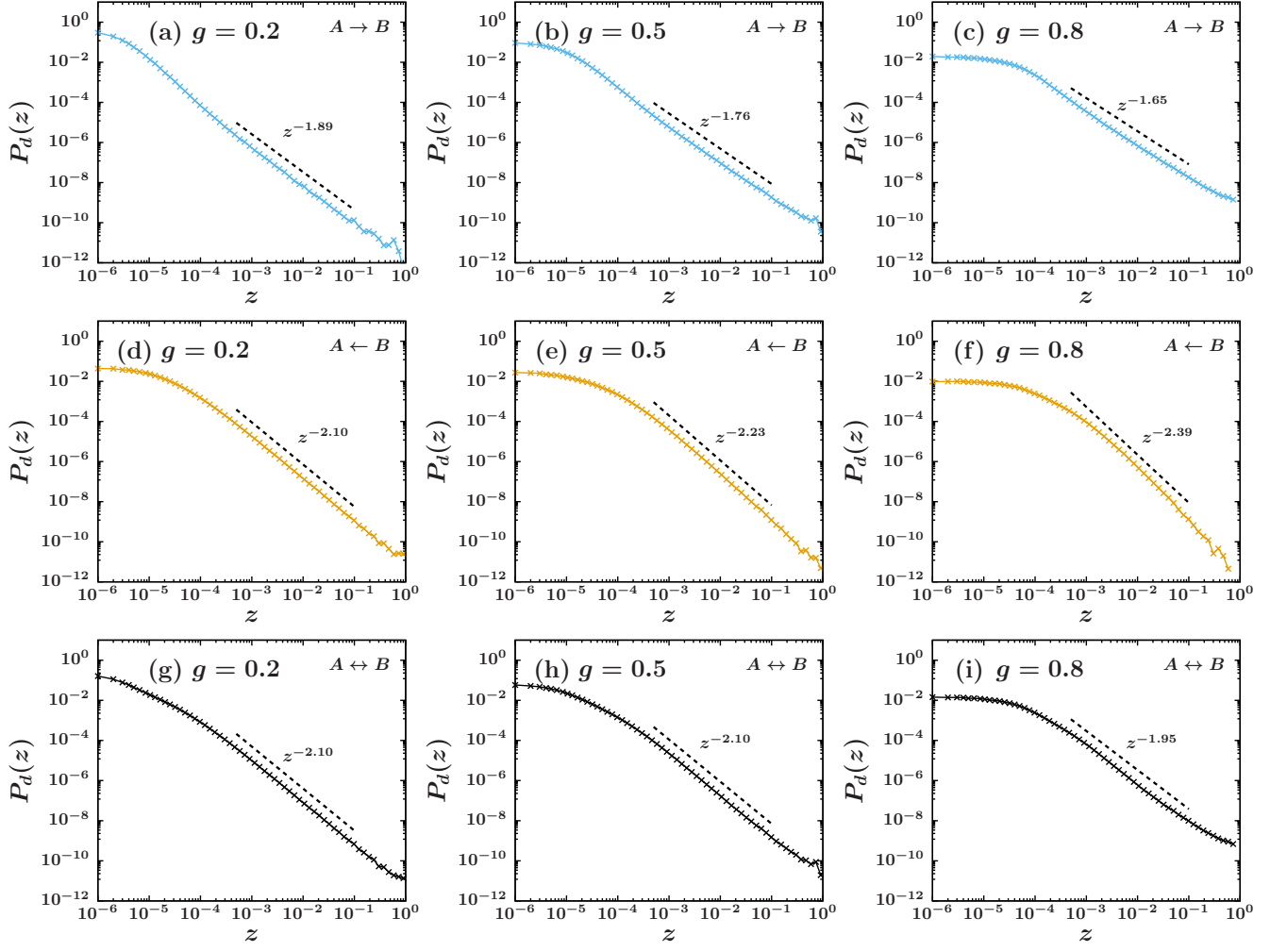


Fig. S7. IET distribution accumulated during the interval $[t_a, t_g]$ versus duration time z . The exponent α is modified only slightly, depending on the direction of switching: (a–c) $P_d^{A \rightarrow B}(z)$, (d–f) $P_d^{A \leftarrow B}(z)$, and (g–i) $P_d^{A \leftrightarrow B}(z)$.

S4. THE AGE DISTRIBUTION IN THE BIRTH-DEATH PROCESS OF ER NETWORKS

Finally, we remark that in the limit $g \rightarrow 1$, the r -ER model reduces to an ordinary ER model with $\tau = 5/2, \sigma = \sigma' = 1/2$. So it is easily checked that the universal relation $\tau + \sigma = 3$ is also satisfied in this limited case. By solving the rate equation numerically, we find that $\langle n_s(t) \rangle_t \equiv \frac{1}{t_c} \int_0^{t_c} n_s(t) dt \sim \frac{1}{t_c} \int_0^{t_c} dt s^{-\tau} f(s(t_c - t)^{1/\sigma}) \sim s^{-\tau-\sigma}$ as shown in the Fig. S8(a). In the ER cluster aggregation process, waiting time roughly corresponds to the birth-to-death age. We find instead of (S24) that the age distribution of nodes follows a heavy tailed distribution $P(a) \sim a^{-(4-\tau-\sigma)} \sim a^{-1}$. The age distribution was accumulated during the whole subcritical regime $t \in [0, 0.5]$, selectively for those nodes in the merging clusters (Fig. S8(b)). The waiting time z of r -ER model is absent in the ER model, but the waiting time can be conceptually extrapolated to the age a in the limit $g \rightarrow 1$. Actually, the age distribution can be also measured for the r -ER model. It reveals that the distribution has the same exponent value, as shown in the Fig. S8(c). We remark that the exponent α is determined in the early time regime, in which clusters are overall small and thus when a cluster in set A is merged with another cluster regardless of from set A or B , it is likely to move to set B . Thus, the age distribution in ER and r -ER models and the IET distributions in r -ER model behave similarly.

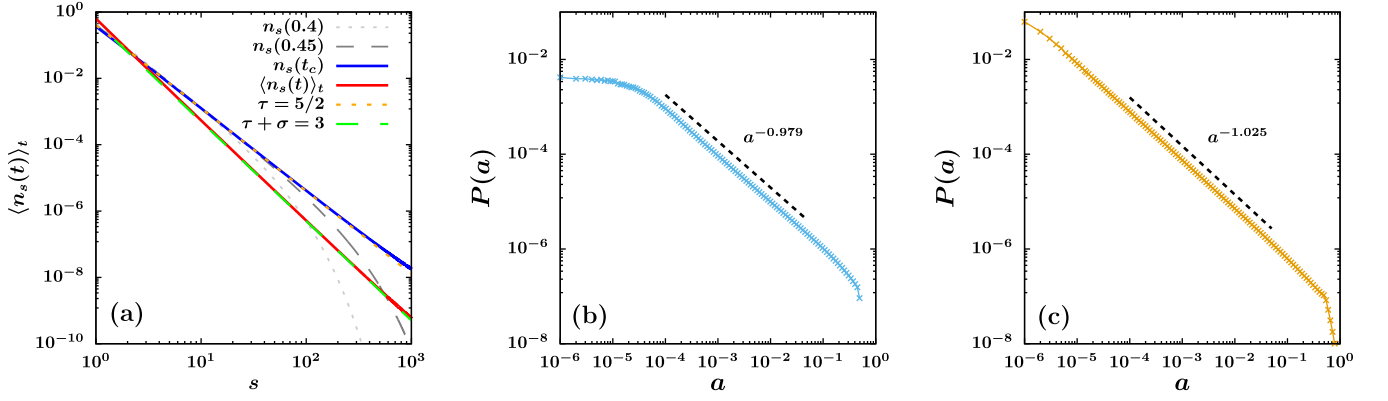


Fig. S8. In the $g \rightarrow 1$ limit, the r -ER model reduces to the ER model which has $n_s(t_c) \sim s^{-\tau}$ with $\tau = 5/2$ at $t_c = 0.5$ and $\sigma = \sigma' = 1/2$. By solving Smoluchowski equation of the ER model we find that (a) $\langle n_s(t) \rangle_t = \frac{1}{t_c} \int_0^{t_c} n_s(t) dt \sim \frac{1}{t_c} \int_0^{t_c} ds s^{-\tau} f(s(t_c - t)^{1/\sigma}) \sim s^{-\tau-\sigma} \sim s^{-3}$ is satisfied. Furthermore, regarding cluster merging of the ER model as a birth-death process we find that (b) the age distribution $P(a)$ exhibits power-law decay with exponent close to 1. In the limit $g \rightarrow 1$, waiting time z can be interpreted as age a . In (b) we accumulate the age distribution of nodes in the merging clusters during $[0, t_c]$ and averaged over 10^4 independent configurations of finite size $N = 10^5$ of ER networks. (c) Distribution of merging intervals $P(a)$ in the r -ER model. $g = 0.2$ and $N = 10^4$ are taken. Data are collected during the time window $[0, t_g]$ and from 10^3 samples.

S5. THE NUMBER OF EVENTS

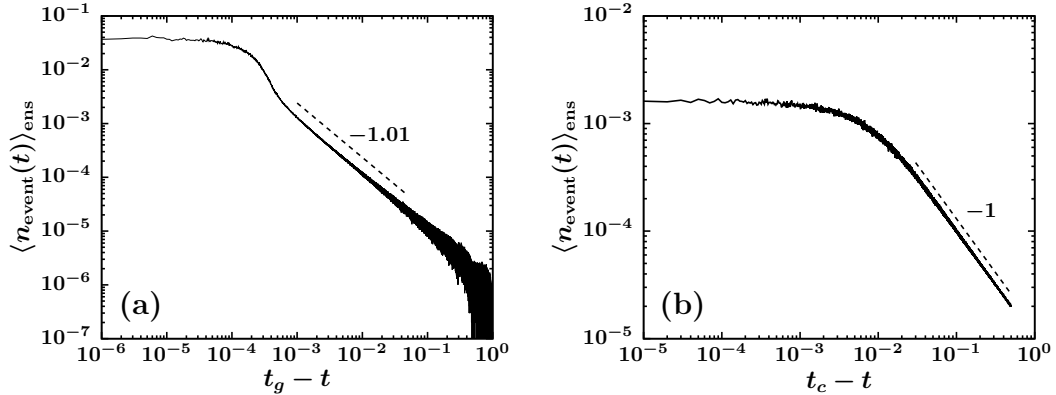


Fig. S9. Plots of $n_{\text{events}}(t) \equiv N_{\text{events}}(t)/N$ vs. $t_g - t$ for (a) the r -ER model with $g = 0.2$ and (b) the ER model. Each figure shows an ensemble averaged curve over 10^3 samples. Both cases show a power-law behavior with exponent one.

S6. THE DEVIL'S STAIRCASE

In this section, we consider the evolution of the largest cluster in the system. At each time t , we measure $m(t)$. For a single configuration, it increases discontinuously like a staircase with irregular steps. We are interested in the distributions of the jump sizes and widths of the staircase. To calculate these distributions, we consider the continuous order parameter $m(t)$ after taking the ensemble average and find the following empirical scaling relation in the intermediate range of m .

$$m(t) \sim (t_c - t)^{-1/\eta}, \quad (\text{S35})$$

and thus

$$\frac{m(t)}{\dot{m}(t)} = \eta(t_c - t) \sim \eta m^{-\eta}. \quad (\text{S36})$$

This power-law behavior is shown in Fig. S10 (d–f).

Next, we consider the width distribution of the staircase. This can be calculated as follows:

$$P_w(\Delta t; t_c) = \int_0^{t_c} dt_0 q(m_{t_0}) \prod_{t=t_0+1/N}^{t_0+\Delta t-1/N} q(m_t) [1 - q(m_{t_0+\Delta t})] \quad (\text{S37})$$

$$= \int_{1/N}^{m_{t_c}} \frac{dm}{\dot{m}} \Big|_{t=t_0} m_{t_0} \prod_{t=t_0+1/N}^{\Delta t-1} (1 - m_{t_0}) m_{t_0} \quad (\text{S38})$$

$$\approx \eta \int_{1/N}^{m_{t_c}} dm m^{1-\eta} e^{-mN(\Delta t-1)} \quad (\text{S39})$$

$$= \eta N^{\eta-2} \int_1^{Nm_{t_c}} dm m^{1-\eta} e^{-m(\Delta t-1)} \quad (\text{S40})$$

$$\simeq \frac{\eta \Gamma(2-\eta)}{(N\Delta t)^{2-\eta}}, \quad (\text{S41})$$

where $q(m_t)$ denotes the probability that a giant cluster at time t has the same size as it did in the previous time step. We use a normalized time and normalized size, so the index t in the product should be increased by $1/N$, and the size of the giant cluster at t_c is $Nm_{t_c} \sim O(N) \rightarrow \infty$ in the thermodynamic limit. Numerically, we obtain $\eta \approx 1$, and thus $P_w(\Delta t) \sim 1/\Delta t$, which is in agreement with the simulation result in Fig. S12 (d–f).

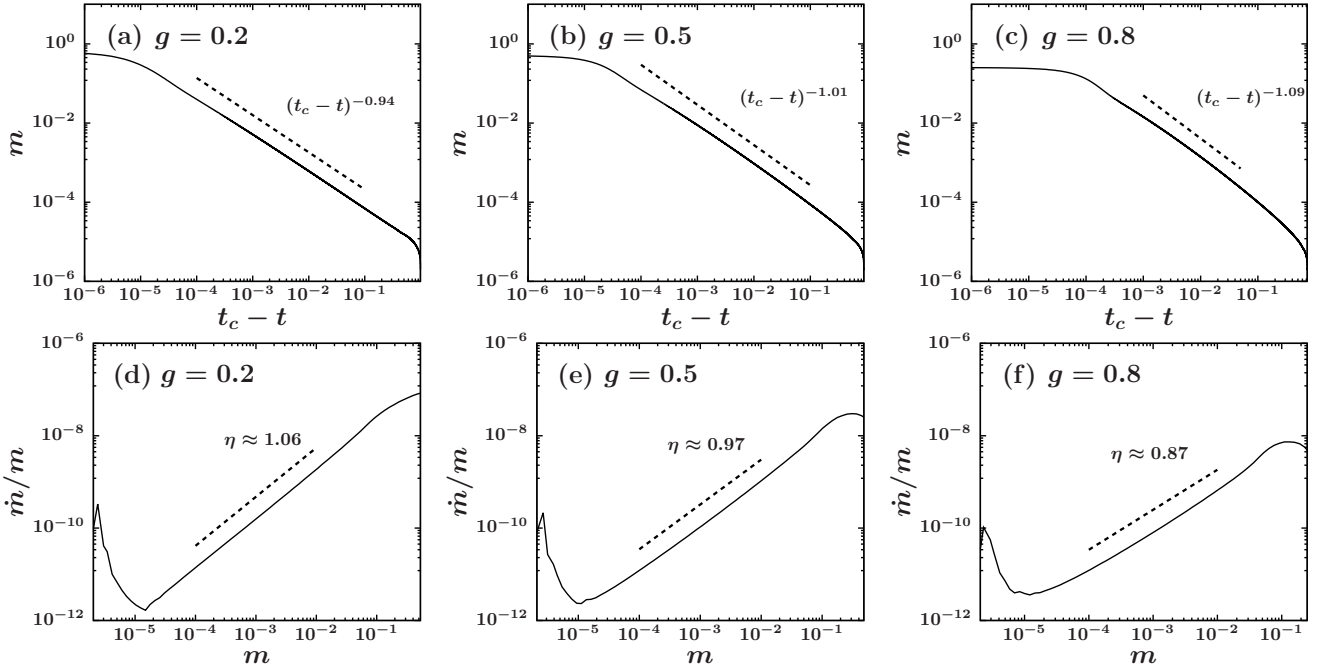


Fig. S10. (a–c) Plot of $m(t)$ versus $t_c - t$ to check $m(t) \sim (t_c - t)^{-1/\eta}$. (d–f) Plot of \dot{m}/m versus m . The curves were averaged over 10^5 configurations. $m(t)$ appears to follow a power law as $m(t) \sim (t_c - t)^{-1/\eta}$ in the intermediate range of m , which corresponds to the jump region. The slope in (d–f) corresponds to the exponent η .

Next, we consider the portion of accumulation in $P_w(\Delta t)$ that is contributed during some limited time window $[t_a, t_c]$. This marginal distribution decays exponentially, in agreement with the simulation results presented in Fig. S12 (d–f)

(orange symbols).

$$\frac{dP_w(\Delta t; t_c)}{dt_c} = \frac{d}{dt_c} \eta \int_{1/N}^{m_{t_c}} dm m^{1-\eta} e^{-mN\Delta t} \quad (\text{S42})$$

$$= \dot{m}_{t_c} \frac{d}{dm_{t_c}} \eta \int_{1/N}^{m_{t_c}} dm m^{1-\eta} e^{-mN\Delta t} \quad (\text{S43})$$

$$= \dot{m}_{t_c} \eta m_{t_c}^{1-\eta} e^{-m_{t_c}N\Delta t} \quad (\text{S44})$$

$$= \frac{1}{\eta} m_{t_c}^{1+\eta} \eta m_{t_c}^{1-\eta} e^{-m_{t_c}N\Delta t} \quad (\text{S45})$$

$$= m_{t_c}^2 e^{-m_{t_c}N\Delta t}. \quad (\text{S46})$$

Moreover, we also consider the jump distribution of the staircase. For intermediate values of Δm after t_a , the stair heights correspond to the giant cluster size increment. We find that the distribution of the giant cluster size increment Δm exhibits crossover behavior. Specifically, it has a power-law tail with an exponent of approximately 1.42 to 1.54 (Fig. S12 (a–c)). The bump around $\Delta m \approx 10^{-2}$ corresponds to the abundance of clusters of size $S_A(t_a)$ at time t_a .

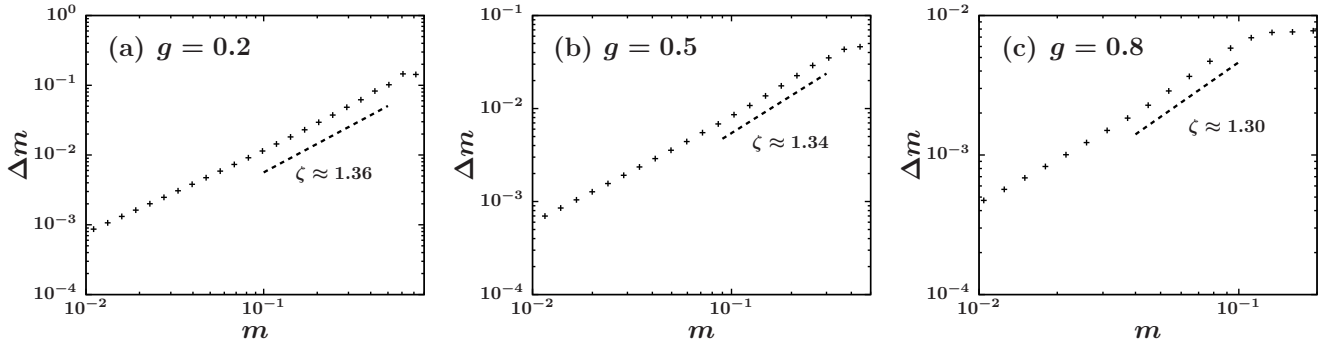


Fig. S11. Δm versus m . The data points averaged over 10^5 configurations are log-binned. The exponent ζ is measured in the intermediate range of m , in which the order parameter increases dramatically. (a) $\zeta = 1.36$, (b) $\zeta = 1.34$, and (c) $\zeta = 1.30$ for $g = 0.2, 0.5, 0.8$, respectively.

From Eq. (S35), $\dot{m} \sim \eta^{-1} m^{1+\eta}$. From Fig. S12 (d–f) (orange data points), we find that $P_{\Delta t}$ decays exponentially. Thus, we regard $P_{\Delta t}$ as a constant and obtain

$$P_{\Delta m} = \frac{P_{\Delta t}}{\Delta m / \Delta t} \sim \frac{P_{\Delta t}}{\dot{m}} \sim \frac{\eta(\text{const})}{m^{1+\eta}} \sim m^{-(1+\eta)} \sim (\Delta m)^{-(1+\eta)/\zeta} \equiv (\Delta m)^{-\delta}, \quad (\text{S47})$$

where ζ is defined as $\Delta m \sim m^\zeta$ at $[t_c^-, t_c]$. In Fig. S10 (g–i), the value of $\zeta(g)$ is measured to be approximately 1.33, and it depends on g . Thus, it is expected that

$$P_{\Delta m} \sim (\Delta m)^{-1.5}.$$

It is worth noting previous results: In an avalanche process such as k -core, and the Bak–Tang–Wiesenfeld model on ER networks, the duration of the avalanche $P_\ell \sim \ell^{-1}$, and the size of the avalanche scales as $P_s \sim s^{-3/2}$. From our result, we find that this is also the case. In fractional percolation, multiplicative growth of the jump size has induced $P_s \sim s^{-1}$, and this was interpreted as indicating that the non-self-averaging property may lead to an exponent that is larger than unity. Further, in Barkhausen percolation, the exponent was 1.5. However, the previously studied underlying mechanism of crackling noise during the avalanche process is not applicable to our model, which is based on dichotomous cluster merging processes.

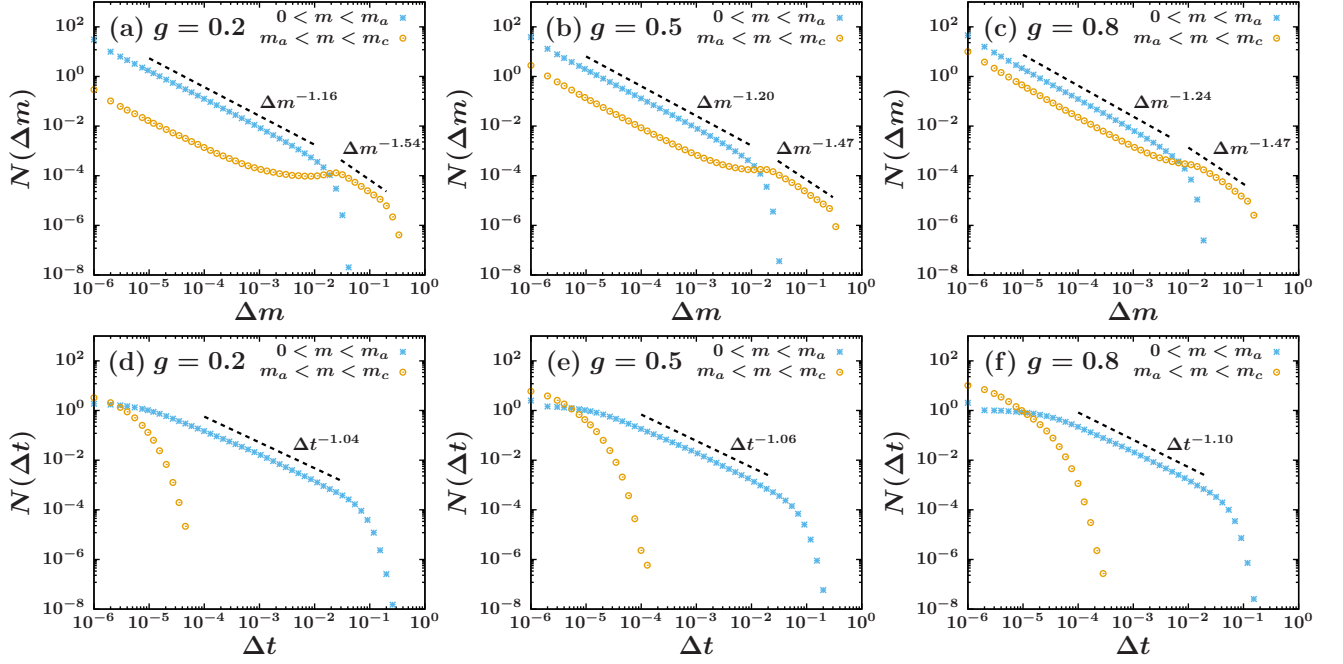


Fig. S12. Distributions of (a–c) step height Δm and (d–f) width Δt . The exponent of $N(\Delta t)$ seems to be independent of g .

S7. TABLE

g	τ^*	τ	σ'	α	α'	δ_1	δ_2	η	ζ
0.2	2.13	2.08	0.974	0.99	2.10	1.16	1.54	1.06	1.36
0.5	2.26	2.18	0.934	0.95	2.10	1.20	1.44	0.97	1.34
0.8	2.35	2.25	0.906	0.88	1.94	1.24	1.42	0.87	1.30

TABLE S1. g is the control parameter representing the fraction of nodes contained in set A . τ^* and τ are the exponents of the cluster size distribution at t_c obtained from an analytic formula [2] and simulations, respectively. σ' is the exponent of the characteristic cluster size s_A . α and α' are the exponents of the IET distribution in the time windows $[0, t_g]$ and $[t_a, t_g]$, respectively. δ_1 and δ_2 are the exponents of the jump size distribution for small and large Δm , respectively. The exponents η and ζ are associated with growth of the largest cluster.

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[2] Y. S. Cho, J. S. Lee, H. J. Herrmann, and B. Kahng, Phys. Rev. Lett. **116**, 025701 (2016).